

Vector Analysis

- Vector Algebra
- Coordinate systems
- Gradient, Divergence, Curl, Del Operator
- The Dirac Delta function
- Helmholtz's Theorem

Vector Algebra

$\vec{A} = \vec{B}$: $|\vec{A}| = |\vec{B}|$ և անունը պահանջման վեհական
($\vec{A} \parallel \vec{B}$) կամ անունը պահանջման վեհական
vector պահանջման վեհական

Vector addition

$$(\alpha + \beta)\vec{A} = \alpha\vec{A} + \beta\vec{A}$$

$$\alpha(\vec{A} + \vec{B}) = \alpha\vec{A} + \alpha\vec{B}$$

$$\vec{A} + \vec{B} = \vec{B} + \vec{A}$$

$$(\vec{A} + \vec{B}) + \vec{C} = \vec{A} + (\vec{B} + \vec{C})$$

+ այսպէս $\vec{A} + \alpha$ (vector + scalar)

Dot Product

$$\vec{A} \cdot \vec{B} = |\vec{A}||\vec{B}| \cos \theta$$

$$0 < \theta < 180^\circ$$

$$(\alpha\vec{A}) \cdot \vec{B} = \vec{A} \cdot (\alpha\vec{B}) = \alpha(\vec{A} \cdot \vec{B})$$

$$\vec{A} \cdot (\vec{B} + \vec{C}) = \vec{A} \cdot \vec{B} + \vec{A} \cdot \vec{C}$$

Cosine law: $C^2 = A^2 + B^2 - 2AB \cos \theta$

$$\vec{C} = \vec{A} - \vec{B}$$

Cross Product

$$|\vec{A} \times \vec{B}| = |\vec{A}||\vec{B}| \sin \theta$$

Right hand rule

$$\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$$

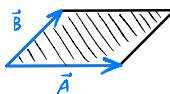
$$\alpha(\vec{A} \times \vec{B}) = (\alpha\vec{A}) \times \vec{B} = \vec{A} \times (\alpha\vec{B})$$

$$\vec{A} \cdot (\vec{B} \times \vec{C}) = (\vec{A} \cdot \vec{B}) + (\vec{A} \cdot \vec{C})$$

$$\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{A} \times \vec{C}) = \vec{C} \cdot (\vec{A} \times \vec{B}) \rightarrow \text{triple products}$$

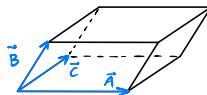
$$|\vec{A} \times \vec{B}|^2 = A^2 B^2 - (\vec{A} \cdot \vec{B})^2 \rightarrow \text{Lagrange's identity}$$

Ուղարկություն պարզաբանելու համար:



$$\text{հանդիսանութեան համար: } |\vec{A} \times \vec{B}|$$

Ուղարկություն պարզաբանելու համար:

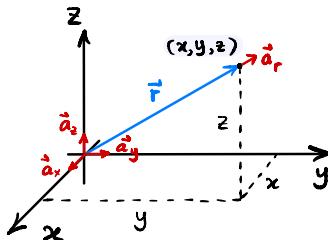


$$\text{պարզաբանելու համար: } |\vec{B} \cdot (\vec{A} \times \vec{C})|$$

Coordinate systems

Cartesian Coordinates

քառակուսագիծ



Position vector:

$$\vec{r} = x\vec{a}_x + y\vec{a}_y + z\vec{a}_z$$

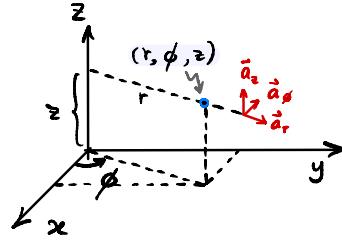
$$\vec{r} = \vec{i} + \vec{j} + \vec{k}$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\vec{a}_r = \frac{\vec{r}}{r}$$

Cylindrical Coordinates

քառակուսագիծ գրական



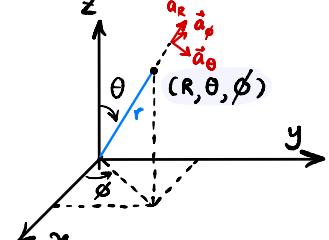
$$x = r \cos \phi \quad r = \sqrt{x^2 + y^2}$$

$$y = r \sin \phi \quad \phi = \arctan\left(\frac{y}{x}\right)$$

$$z = z \quad z = z$$

Spherical Coordinates

քառակուսագիծ գրական



$$x = R \sin \theta \cos \phi \quad R = \sqrt{x^2 + y^2 + z^2}$$

$$y = R \sin \theta \sin \phi \quad \theta = \arccos\left(\frac{z}{R}\right)$$

$$z = R \cos \theta \quad \phi = \arctan\left(\frac{y}{x}\right)$$

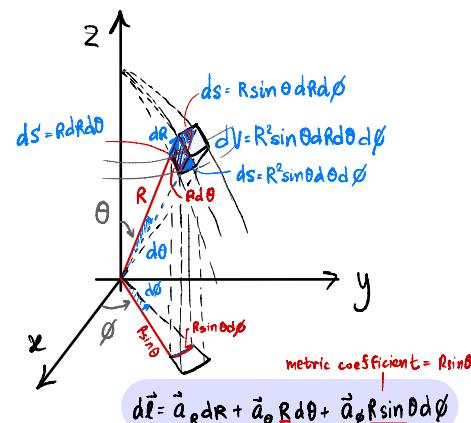
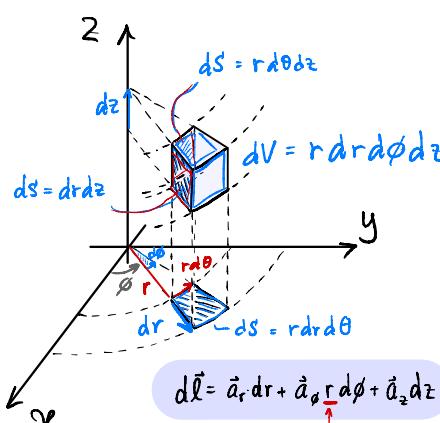
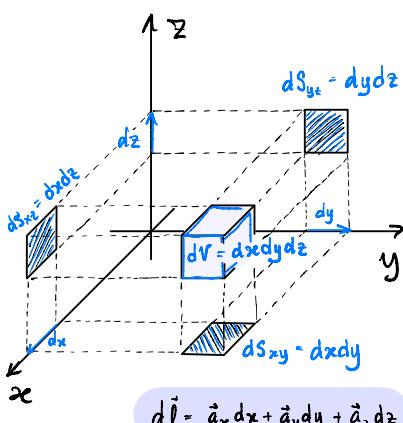
Unit vector conversion:

| | |
|--|---|
| $\vec{a}_x = \vec{a}_r \cos \phi - \vec{a}_\theta \sin \phi$ | $\vec{a}_r = \vec{a}_x \cos \phi + \vec{a}_y \sin \phi$ |
| $\vec{a}_y = \vec{a}_r \sin \phi + \vec{a}_\theta \cos \phi$ | $\vec{a}_\theta = -\vec{a}_x \sin \phi + \vec{a}_y \cos \phi$ |
| $\vec{a}_z = \vec{a}_z$ | $\vec{a}_z = \vec{a}_z$ |

| | |
|--|--|
| $\vec{a}_r = \vec{a}_x \sin \theta \cos \phi + \vec{a}_y \sin \theta \sin \phi - \vec{a}_z \cos \theta$ | $\vec{a}_\theta = \vec{a}_x \cos \theta \cos \phi + \vec{a}_y \cos \theta \sin \phi + \vec{a}_z \sin \theta$ |
| $\vec{a}_\phi = \vec{a}_x \sin \theta \sin \phi + \vec{a}_y \cos \theta \sin \phi + \vec{a}_z \cos \theta$ | $\vec{a}_\phi = -\vec{a}_x \sin \theta + \vec{a}_y \cos \theta$ |

| կայունություն | \vec{a}_x | \vec{a}_y | \vec{a}_z |
|------------------|--------------|-------------|-------------|
| \vec{a}_r | $\cos \phi$ | $\sin \phi$ | 0 |
| \vec{a}_θ | $-\sin \phi$ | $\cos \phi$ | 0 |
| \vec{a}_z | 0 | 0 | 1 |

| կայունություն | \vec{a}_x | \vec{a}_y | \vec{a}_z |
|------------------|-------------------------|-------------------------|----------------|
| \vec{a}_r | $\sin \theta \cos \phi$ | $\sin \theta \sin \phi$ | $\cos \theta$ |
| \vec{a}_θ | $\cos \theta \cos \phi$ | $\cos \theta \sin \phi$ | $-\sin \theta$ |
| \vec{a}_ϕ | $-\sin \phi$ | $\cos \phi$ | 0 |



(ex) Find the surface integral of \vec{a}_r (cylindrical coordinates) when the surface is a unit circle.

Soln

$$\iint_{\text{unit circle}} \vec{a}_r \cdot dS = \int_0^{\pi/2} \int_0^1 \vec{a}_r \cdot r dr d\phi$$

$$= \int_0^{\pi/2} \int_0^1 (a_x \cos \phi + a_y \sin \phi) r dr d\phi$$

(ex) Find the total interaction from the given surface.

$$\text{Surface: } r = R \sin \theta$$

$$\text{Volume: } V = \frac{1}{3} \pi R^2 h$$

$$\text{Surface area: } S = \pi R^2$$

$$\text{Surface integral: } \iint_S f(r, \theta, \phi) r dr d\theta d\phi$$

$$= \int_0^{\pi/2} \int_0^{\pi/4} f(R, \theta, \phi) R^2 \sin \theta d\theta d\phi$$

$$= \int_0^{\pi/2} \int_0^{\pi/4} f(R, \theta, \phi) R^2 \sin \theta d\theta d\phi$$

► Gradient of a Scalar Field

[Scalar \rightarrow Vector]

$$\nabla T = \text{grad } T = \vec{a}_u_1 \frac{\partial T}{\partial u_1} + \vec{a}_u_2 \frac{\partial T}{\partial u_2} + \vec{a}_u_3 \frac{\partial T}{\partial u_3}$$

Del operator

$$\nabla = \vec{a}_{u_1} \frac{\partial}{\partial u_1} + \vec{a}_{u_2} \frac{\partial}{\partial u_2} + \vec{a}_{u_3} \frac{\partial}{\partial u_3}$$

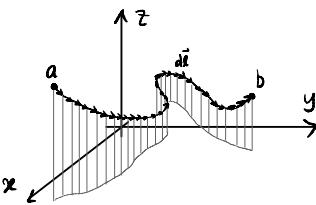
metric coefficient
รากสี่เหลี่ยมค่าคงที่

$$\nabla T = \vec{a}_x \frac{\partial T}{\partial x} + \vec{a}_y \frac{\partial T}{\partial y} + \vec{a}_z \frac{\partial T}{\partial z} \quad (\text{Cartesian})$$

$$\nabla T = \vec{a}_r \frac{\partial T}{\partial r} + \vec{a}_\theta \frac{1}{r} \frac{\partial T}{\partial \theta} + \vec{a}_\phi \frac{1}{r \sin \theta} \frac{\partial T}{\partial \phi} \quad (\text{Cylindrical})$$

$$\nabla T = \vec{a}_R \frac{\partial T}{\partial R} + \vec{a}_\theta \frac{1}{R} \frac{\partial T}{\partial \theta} + \vec{a}_\phi \frac{1}{R \sin^2 \theta} \frac{\partial T}{\partial \phi} \quad (\text{Spherical})$$

② The Fundamental Theorem for Gradients



$$\int_a^b (\nabla T) \cdot d\vec{r} = T(b) - T(a)$$

Corollaries:

- ① $\int_a^b (\nabla T) \cdot d\vec{r} \equiv \text{พื้นที่ในพื้นที่ทางจาก } a \text{ ไป } b$
- ② $\oint (\nabla T) \cdot d\vec{r} = 0$ (วงกลมบรรจบกัน)

**note: ถ้าหากเราหาต้นต่อตัวเดียวกัน \vec{N} ทุกจุด $\vec{N} = \nabla \phi$ (e) Find the gradient of $r = \sqrt{x^2 + y^2 + z^2}$ (position vector)

$$\text{Soln} \quad \nabla r = \vec{a}_x \frac{\partial r}{\partial x} + \vec{a}_y \frac{\partial r}{\partial y} + \vec{a}_z \frac{\partial r}{\partial z} = \frac{x \vec{a}_x + y \vec{a}_y + z \vec{a}_z}{\sqrt{x^2 + y^2 + z^2}} = \frac{\vec{r}}{r} = \vec{a}_r$$

+ หมายความว่าในทิศทางที่ r ดัดแปลงอยู่ใน radial direction ทำให้ความเร็วเป็น 1(e) Check the fundamental theorem for gradients, using $T = x^2 + 4xy + 2z^3$, the point $a = (0,0,0)$, $b = (1,1,1)$ and the following paths:

$$\text{Soln} \quad T(b) - T(a) = 7 - 0 = 7$$

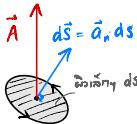
$$\nabla T = (2x+4y)\vec{a}_x + (4x+2z^2)\vec{a}_y + (6z^2)\vec{a}_z$$

$$\begin{aligned} (a) \int_a^b (\nabla T) \cdot d\vec{r} &= \int_a^b (T(r) - T(r')) dt \\ &= \int_0^1 dt + \int_0^1 dt + \int_0^1 dt \\ &= 1 + 4 + 2 = 7 \end{aligned}$$

$$\begin{aligned} (b) \int_a^b (\nabla T) \cdot d\vec{r} &= \int_a^b (\nabla T) \cdot \vec{F} dt \\ &= \int_0^1 (2t+4t^2) dt + (4t+2t^2) dt \\ &= (t, t^2, t^3) \quad \vec{F} = (t, t^2, t^3) \\ &= (1, 1, 1) \quad \vec{F}' = (1, 1, 1) \\ &= 2+5=7 \end{aligned}$$

$$\therefore \int_a^b (\nabla T) \cdot d\vec{r} = T(b) - T(a) \quad \blacksquare$$

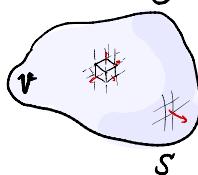
► Divergence of a Vector Field



$$\text{flux ของ } \vec{A} \text{ ผ่าน } ds = \vec{A} \cdot d\vec{s}$$

[vector \rightarrow scalar]

□ Divergence Theorem

Total flux ของ \vec{A} ผ่าน S

$$\iiint_V (\nabla \cdot \vec{A}) \cdot dV = \iint_S \vec{A} \cdot d\vec{s}$$

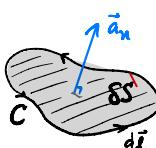
Volume integral ของ $\nabla \cdot \vec{A}$ (e) Evaluate $\int_V (\frac{\cos^2 \theta}{R^3} \vec{a}_R) dV$ & $\oint_S \frac{\cos^2 \theta}{R^3} \vec{a}_R \cdot d\vec{s}$ Where V is the volume of the hollow spherebounded by $R=1$ and $R=3$ and S is the surface enveloped V 

$$\text{Soln: } D = \nabla \cdot \frac{\cos^2 \theta}{R^3} \vec{a}_R = \frac{1}{R^3} \frac{2}{R} \left(R^2 \cos^2 \theta \right) = -\frac{\cos^2 \theta}{R^4} \rightarrow \text{Ans}$$

$$\begin{aligned} \int_V (D) dV &= \int_0^{2\pi} \int_0^{\pi} \int_1^3 \left(-\frac{\cos^2 \theta}{R^4} \right) R^2 \sin \theta dR d\theta d\phi \\ &= \int_0^{2\pi} \cos^2 \theta d\theta \int_0^{\pi} \sin \theta d\theta \int_1^3 R^2 dR \\ &= (\pi)(2)(-\frac{1}{2}) = -\pi \quad \text{Ans} \end{aligned}$$

$$\begin{aligned} \oint_S (\frac{\cos^2 \theta}{R^3} \vec{a}_R) \cdot d\vec{s} &= \int_0^{2\pi} \int_0^{\pi} \int_0^1 \left(\frac{\cos^2 \theta}{R^3} \right)^2 \sin \theta d\theta d\phi \\ &= \frac{1}{2} \int_0^{2\pi} \cos^2 \theta d\theta \int_0^{\pi} \sin^2 \theta d\theta - \int_0^{2\pi} \cos^2 \theta d\theta \int_0^1 \sin \theta d\theta \\ &= -\frac{1}{2} \int_0^{2\pi} \cos^2 \theta d\theta \int_0^1 \sin \theta d\theta \\ &= -\frac{1}{2} (\pi)(2) = -\pi \quad \text{Ans} \end{aligned}$$

► Curl of a Vector Field



$$\text{line integral ของ } \vec{A} \text{ บนเส้น } C = \lim_{SS \rightarrow 0} \frac{\oint_C \vec{A} \cdot d\vec{r}}{SS}$$

[vector \rightarrow vector]
ด้านล่างนี้จะเขียนว่า $\int_C \vec{A} \cdot d\vec{r}$

⇒ น้ำหนักการหมุนรอบแกนต้องมีเท่ากัน

(vector \rightarrow scalar) \Rightarrow Irrotational field/Conservative field

$$\nabla \times \vec{A} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} \vec{a}_{u_1} h_1 & \vec{a}_{u_2} h_2 & \vec{a}_{u_3} h_3 \\ \frac{\partial}{\partial u_1} & \frac{\partial}{\partial u_2} & \frac{\partial}{\partial u_3} \\ h_1 A_1 & h_2 A_2 & h_3 A_3 \end{vmatrix}$$

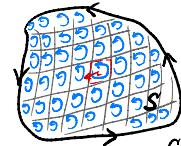
$$\vec{A} = A_1 \vec{a}_{u_1} + A_2 \vec{a}_{u_2} + A_3 \vec{a}_{u_3}$$

$$\nabla \times \vec{A} = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} \quad (\text{Cartesian})$$

$$\nabla \times \vec{A} = \frac{1}{r} \begin{vmatrix} \vec{a}_r & \vec{a}_\theta & \vec{a}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & r A_\theta & A_\phi \end{vmatrix} \quad (\text{Cylindrical})$$

$$\nabla \times \vec{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \vec{a}_R & \vec{a}_\theta & \vec{a}_\phi \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_R & R A_\theta & R \sin \theta A_\phi \end{vmatrix} \quad (\text{Spherical})$$

□ Stoke's Theorem

Line integral ของ \vec{A} บน C ก็เท่ากับ

$$\iint_S (\nabla \times \vec{A}) \cdot d\vec{s} = \oint_C \vec{A} \cdot d\vec{r}$$

Surface integral ของ $\nabla \times \vec{A}$

Corollaries:

$$\textcircled{1} \quad \oint_S (\nabla \times \vec{A}) \cdot d\vec{s} \equiv \text{พื้นที่ในพื้นที่ทางจาก } S \text{ ไป } S$$

$$\textcircled{2} \quad \oint_S (\nabla \times \vec{A}) \cdot d\vec{s} = 0 \quad \text{เมื่อ } S \text{ เป็นปิดไม่มีรูร่อง}$$

(e) จงหา curl ของ \vec{A} ที่ S ที่ C ล้อม

$$\begin{aligned} \vec{A}_a &= -y \vec{a}_x + x \vec{a}_y \\ \vec{A}_b &= x \vec{a}_z \\ \vec{A}_c &= z \vec{a}_z \end{aligned}$$

$$\begin{aligned} \nabla \times \vec{A}_a &= \frac{\partial}{\partial x} \frac{\partial}{\partial y} \frac{\partial}{\partial z} \\ &= \frac{\partial}{\partial x} \frac{\partial}{\partial y} 0 = 2 \vec{a}_z \end{aligned}$$

$$\begin{aligned} \nabla \times \vec{A}_b &= \frac{\partial}{\partial x} \frac{\partial}{\partial y} \frac{\partial}{\partial z} \\ &= \frac{\partial}{\partial x} \frac{\partial}{\partial y} 0 = 0 \vec{a}_z \end{aligned}$$

$$\begin{aligned} \nabla \times \vec{A}_c &= \frac{\partial}{\partial x} \frac{\partial}{\partial y} \frac{\partial}{\partial z} \\ &= \frac{\partial}{\partial x} \frac{\partial}{\partial y} 0 = 0 \vec{a}_z \end{aligned}$$

$$\begin{aligned} \text{Find the curl of } \vec{A} = 5e^r \cos \theta \vec{a}_r - 5 \cos \theta \vec{a}_\theta \\ \nabla \times \vec{A} = \frac{1}{r} \begin{vmatrix} \vec{a}_r & \vec{a}_\theta & \vec{a}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 5e^r \cos \theta & 0 & -5 \cos \theta \end{vmatrix} \end{aligned}$$

$$= \frac{5e^r \cos \theta}{r} \vec{a}_\phi + \frac{5e^r \sin \theta}{r} \vec{a}_\phi = 0 \vec{a}_\phi$$

$$\begin{aligned} \text{Given } \vec{A} &= 6R \sin \theta \vec{a}_r + 18 R \sin \theta \cos \theta \vec{a}_\theta \\ \text{Evaluate } \iint_S (\nabla \times \vec{A}) \cdot d\vec{s} &= \oint_C \vec{A} \cdot d\vec{r} \quad \text{Where } S \text{ is bounded by a cone } \theta = \frac{\pi}{10}, R=2, R=4 \\ &= \int_0^{2\pi} \int_0^{\pi/10} \left(6R \sin \theta \vec{a}_r + 18 R \sin \theta \cos \theta \vec{a}_\theta \right) \cdot \left(R \sin \theta R d\theta d\phi \vec{a}_\phi \right) \\ &= \int_0^{2\pi} \int_0^{\pi/10} \left(6R^2 \sin^2 \theta \cos \theta \vec{a}_\phi + 18 R^2 \sin^2 \theta \vec{a}_\phi \right) \cdot \left(R \sin \theta R d\theta d\phi \vec{a}_\phi \right) \\ &= \int_0^{2\pi} \int_0^{\pi/10} 12R^3 \sin^3 \theta \cos \theta d\theta d\phi = 12.44 \end{aligned}$$

► Del Operator Identities

- (1) $\nabla(fg) = f(\nabla g) + g(\nabla f)$
- (2) $\nabla(\vec{A} \cdot \vec{B}) = \vec{A} \times (\nabla \times \vec{B}) + \vec{B} \times (\nabla \times \vec{A}) + (\vec{A} \cdot \nabla) \vec{B} + (\vec{B} \cdot \nabla) \vec{A}$
- (3) $\nabla \cdot (\vec{f}\vec{A}) = \vec{f} \cdot (\nabla \cdot \vec{A}) + \vec{A} \cdot (\nabla \vec{f})$
- (4) $\nabla \times (\vec{A} \times \vec{B}) = \vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B})$
- (5) $\nabla \times (\vec{f}\vec{A}) = \vec{f}(\nabla \times \vec{A}) - \vec{A} \times (\nabla \vec{f})$
- (6) $\nabla \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} - (\vec{A} \cdot \nabla) \vec{B} + \vec{A}(\nabla \cdot \vec{B}) - \vec{B}(\nabla \cdot \vec{A})$
- (7) $\nabla \times (\nabla f) = 0$: Curl-free, irrotational, conservative field
- (8) $\nabla \cdot (\nabla \times \vec{A}) = 0$: Divergenceless, solenoidal field
- (9) $\nabla \cdot (\nabla T) = \nabla^2 T$ Laplacian
- (10) $\nabla \times (\nabla \times \vec{A}) = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$

► Laplacian

Scalar: $\nabla^2 T = \nabla \cdot (\nabla T)$

Vector: $\nabla^2 \vec{A} = \nabla(\nabla \cdot \vec{A}) - \nabla \times (\nabla \times \vec{A}) = \frac{\partial^2 \vec{A}}{\partial x^2} + \frac{\partial^2 \vec{A}}{\partial y^2} + \frac{\partial^2 \vec{A}}{\partial z^2}$ (Cartesian)

Scalar: $\nabla^2 T = \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2}$ (Cartesian)

Cylindrical: $\nabla^2 T = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \theta^2} + \frac{\partial^2 T}{\partial z^2}$ (Cylindrical)

Spherical: $\nabla^2 T = \frac{1}{R^2} \frac{\partial}{\partial R} \left(R^2 \frac{\partial T}{\partial R} \right) + \frac{1}{R^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{R^2 \sin^2 \theta} \frac{\partial^2 T}{\partial \phi^2}$ (Spherical)

② Calculate the Laplacian of the following functions.

- (a) $T_a = x^2 + 2xy + 3z + 4 \rightarrow \nabla^2 T_a = 2 + 0 + 0 = 2$
- (b) $T_b = \sin x \sin y \sin z \rightarrow \nabla^2 T_b = -3 \sin x \sin y \sin z$
- (c) $T_c = e^{-5x} \sin 4y \sin 3z \rightarrow \nabla^2 T_c = 25e^{-5x} \sin 4y \sin 3z - 16e^{-5x} \sin 4y \sin 3z - 9e^{-5x} \sin 4y \sin 3z = 0$
- (d) $\vec{D} = x^2 \hat{a}_x + 3xz \hat{a}_y - 2x^2 \hat{a}_z \rightarrow (2\hat{a}_x) + (0) + (6xz\hat{a}_y) = 2\hat{a}_x + 6xz\hat{a}_y$

► The Dirac Delta Function

The one-dimensional Dirac Delta Function

$$\delta(x) = \begin{cases} 0, & x \neq 0 \\ \infty, & x = 0 \end{cases} \quad \text{if } \int_{-\infty}^{\infty} \delta(x) dx = 1$$

$$\int_{-\infty}^{\infty} f(x) \delta(x-a) dx = f(a)$$

The three-dimensional Dirac Delta Function

$$\delta^3(\vec{r}) = 8(x \delta xy) \delta(z) \quad \text{if } \int_{\text{all space}} \delta^3(\vec{r}) d\vec{r} = 1$$

Position vector: $\vec{r} = x\hat{a}_x + y\hat{a}_y + z\hat{a}_z$

$$\int_{\text{all space}} f(\vec{r}) \delta^3(\vec{r} - \vec{a}) d\vec{r} = f(\vec{a})$$

③ Find $\nabla \cdot \left(\frac{1}{R^2} \hat{a}_R \right) = \nabla \cdot \left(\frac{\vec{r}}{R^3} \right)$

Sol: $\nabla \cdot \left(\frac{1}{R^2} \hat{a}_R \right) = \frac{1}{R^3} \frac{\partial}{\partial R} \left(\frac{R^3}{R^2} \right) = 0$

เราใช้ที่นี่ว่า \hat{a}_R เป็นหนึ่งในสามแกนที่ต้องคำนึงถึง

เราใช้ที่นี่ว่า $\frac{1}{R^2} \hat{a}_R$ เป็นหนึ่งในสามแกนที่ต้องคำนึงถึง

ดังนั้น $\int_V \left(\frac{1}{R^2} \hat{a}_R \right) d\vec{r} = \phi_s \left(\frac{1}{R^2} \hat{a}_R \right) d\vec{s}$

$$= \int_0^{2\pi} \int_0^\pi \frac{1}{R^2} R^2 \sin \theta d\theta d\phi = 4\pi - (1)$$

หากนับรวมๆ $\nabla \cdot \left(\frac{1}{R^2} \hat{a}_R \right)$ ตาม 0 ขนาดในหน้าที่นี่ ก็ได้

$$\text{จาก (*) ให้ } \int_{\text{all space}} \delta^3(\vec{r}) d\vec{r} = 1 \Rightarrow \nabla \cdot \left(\frac{1}{R^2} \hat{a}_R \right) = 4\pi \delta^3(\vec{r})$$

► Helmholtz's Theorem

A vector field (vector point function) is determined to within an additive constant if both its divergence and its curl are specified everywhere.

สมมุติ \vec{F} กำหนดโดยการให้ $\vec{F} = -\nabla V + \nabla \times \vec{A}$

irrotational ($\nabla \cdot \vec{F} = 0$)

solenoidal ($\nabla \cdot \vec{A} = 0$)

④ $\vec{F} = \hat{a}_x(3y - c_1z) + \hat{a}_y(c_2x - 2z) - \hat{a}_z(c_3y + z)$

(a) Determine the constant c_1, c_2, c_3 if \vec{F} is irrotational.

(b) Determine the scalar potential function V . ($\vec{F} = -\nabla V$)

Sol: (a) \vec{F} is irrotational $\therefore \nabla \times \vec{F} = 0$ $\vec{F} = -\nabla V = -\hat{a}_x \frac{\partial V}{\partial x} - \hat{a}_y \frac{\partial V}{\partial y} - \hat{a}_z \frac{\partial V}{\partial z}$

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3y - c_1z & c_2x - 2z & -c_3y - z \end{vmatrix} = \begin{bmatrix} -c_3 + 2 \\ -c_1 \\ c_2 - 3 \end{bmatrix}$$

$$\therefore c_1 = 0, c_2 = 3, c_3 = 2$$

$$\therefore V = -3xy + 2yz + \frac{z^2}{2}$$

Additional Problems

① Let \vec{r} be the separation vector from a fixed point (x', y', z') to the point (x, y, z) and let r be its length. Show that

$$(a) \nabla(r^2) = 2\vec{r}$$

$$(b) \nabla(1/r) = -\hat{a}_r/r^2$$

(c) What is the general formula for $\nabla(r^k)$?

Sol: $\vec{r} = (x-x')\hat{a}_x + (y-y')\hat{a}_y + (z-z')\hat{a}_z$

$$(a) \nabla(r^2) = \nabla \left[(x-x')^2 + (y-y')^2 + (z-z')^2 \right] = 2(x-x')\hat{a}_x + 2(y-y')\hat{a}_y + 2(z-z')\hat{a}_z = 2\vec{r}$$

$$(b) \nabla(1/r) = \nabla \left(\frac{1}{\sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2}} \right) = -\frac{(x-x')\hat{a}_x + (y-y')\hat{a}_y + (z-z')\hat{a}_z}{(x-x')^2 + (y-y')^2 + (z-z')^2} = -\frac{\vec{r}}{r^3}$$

$$(c) \nabla(r^k) = \nabla \left[[(x-x')^2 + (y-y')^2 + (z-z')^2]^{\frac{k}{2}} \right] = k[(x-x')^2 + (y-y')^2 + (z-z')^2]^{\frac{k-2}{2}} \times [(x-x')\hat{a}_x + (y-y')\hat{a}_y + (z-z')\hat{a}_z] = k r^{k-2} \vec{r} = n r^{k-1} \hat{a}_r$$

② Assuming that a cloud of electrons confined in a region between two spheres of radii 2 and 5 cm has a charge density of $\rho = \frac{-3 \times 10^8 \cos^2 \phi}{R^4}$ (C/m^3) find the total charge contained in the region.

Sol: Q = $\int_V \rho dV = \int_0^{2\pi} \int_0^\pi \int_{0.02}^{0.05} \left(\frac{-3 \times 10^8 \cos^2 \phi}{R^4} \right) R^2 \sin \theta dR d\theta d\phi$
 $= -3 \times 10^8 \int_0^{2\pi} \cos^2 \phi d\phi \int_0^\pi \sin \theta d\theta \int_{0.02}^{0.05} \frac{1}{R^2} dR$
 $= (-3 \times 10^8)(\pi)(2)(30) = -1.8\pi \mu C$

③ Given $\vec{F} = \vec{a}_R kR$, determine whether the divergence theorem holds for the shell region enclosed by spherical surfaces at $R=R_1$ and $R=R_2$ ($R_2 > R_1$) centered at the origin.

Sol: $\nabla \cdot \vec{F} = \frac{1}{R^2} \frac{\partial}{\partial R} (R^2 k R) = sk$
 $\int_V (\nabla \cdot \vec{F}) dV = \int_0^{2\pi} \int_0^\pi \int_{R_1}^{R_2} 3k R^2 \sin \theta d\theta d\phi dR$
 $= 3k \int_0^{2\pi} d\phi \int_0^\pi \sin \theta d\theta \int_{R_1}^{R_2} R^2 dR = 4k\pi(R_2^3 - R_1^3)$
 $\oint_S \vec{F} \cdot d\vec{s} = \int_0^{2\pi} \int_0^\pi (\vec{a}_R k R) \cdot \hat{a}_R R^2 \sin \theta d\theta d\phi + \int_0^{2\pi} \int_0^\pi (\vec{a}_R k R) \cdot (-\vec{a}_R R^2 \sin \theta) d\theta d\phi$
 $= k(R_2^3 - R_1^3) \int_0^{2\pi} d\phi \int_0^\pi \sin \theta d\theta = 4k\pi(R_2^3 - R_1^3)$

④ Find the divergence and curl of the function $\vec{A} = r(2 + \sin \phi) \hat{a}_r + r \sin \phi \cos \phi \hat{a}_\theta + r^2 \hat{a}_z$

Sol: $\nabla \cdot \vec{A} = \frac{1}{r} \frac{\partial}{\partial r} (r^2 \sin \phi \cos \phi) + \frac{1}{r} \frac{\partial}{\partial \theta} (r \sin \phi \cos \phi) + \frac{\partial}{\partial z} (r^2)$
 $= 4 + 2 \sin \phi + \cos^2 \phi - \sin^2 \phi + 3$
 $= 7 + \sin^2 \phi + \cos^2 \phi = 8$

$$\nabla \times \vec{A} = \frac{1}{r} \begin{vmatrix} \hat{a}_r & \hat{a}_\theta & \hat{a}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ r(2 + \sin \phi) & r \sin \phi \cos \phi & 2z \end{vmatrix} = \vec{0}$$

⑤ Show that $\vec{F} = y\hat{a}_x + z\hat{a}_y + xy\hat{a}_z$ can be written both as the gradient of a scalar and a curl of vector. Find the scalar and vector potentials for \vec{F} .

Sol: $\nabla \cdot \vec{F} = \frac{\partial}{\partial x}(y) + \frac{\partial}{\partial y}(z) + \frac{\partial}{\partial z}(xy) = 0$ (1)

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & z & xy \end{vmatrix} = 0$$
 (2)

From (1), (2) : $\vec{F} = -\nabla V + \nabla \times \vec{A}$

$$\vec{F} = -\nabla V \Rightarrow \begin{cases} \frac{\partial V}{\partial x} = y \\ \frac{\partial V}{\partial y} = z \\ \frac{\partial V}{\partial z} = xy \end{cases}$$

$$\vec{F} = \nabla \times \vec{A} \Rightarrow \begin{cases} \frac{\partial A_x}{\partial y} = y \\ \frac{\partial A_x}{\partial z} = x \\ \frac{\partial A_y}{\partial x} = xy \end{cases}$$

∴ $V = xyz$ (3)

$$\vec{A} = \frac{1}{2} (x^2y^2z^2) \hat{a}_x + y(x^2z^2) \hat{a}_y + z(y^2x^2) \hat{a}_z$$
 (not unique)